



超曲面のオイラー・ポアンカレ特性類について

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Remarks on the Euler-Poincaré Characteristic of a Hypersurface

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§ 1. Preliminaries.

1. Generalized Gauss-Bonnet formula.

Let M be a compact orientable Riemannian manifold of an even dimension n(=2m) throughout this paper. The Euler-Poincaré characteristic $\chi(M)$ of M is given by

(1)
$$\chi(M) = (2/c_n) \int_M K_n dV,$$

where c_n is the volume of the Euclidian unit *n*-sphere, K_n donetes the Lipschitz-Killing curvature of M and dV is the volume element of M. This formula is called the generalized Gauss-Bonnet formula ([2], [3], [4]).

2. The Gauss equation for a hypersurface.

Let \overline{M} be an (n+1)-dimensional Riemannian manifold covered by a system of coordinate neighborhoods $\{V; x^{\lambda}\}$ and $g_{\lambda\mu}$ and $\overline{R}_{\lambda\mu\nu\omega}$, the metric tensor and the curvature tensor respectively.

Let M be covered by a system of coordinate neighborhoods $\{U; u^a\}$ and g_{ab} and R_{abcd} , the metric tensor and curvature tensor of M respectively. Let M be immersed in \overline{M} and

$$x^{\lambda} = x^{\lambda}(u^{a})$$

be the local parametric expression of M.

Throughout this paper, Greek indices run over the range $\{1, 2, ..., n+1\}$ and Latin indices the range $\{1, 2, ..., n\}$.

If we put

(2) $B_a^{\lambda} = \partial_a x^{\lambda}, \ \partial_a = \partial/\partial u^a,$

then, the Riemannian metric of M induced from that of \overline{M} is given by

(3) $g_{ab} = \overline{g}_{\lambda\mu} B^{\lambda}_{a} B^{\mu}_{b},$

and the equations of Gauss are presented by

(4)
$$R_{abcd} = \overline{R}_{\lambda\mu\nu\omega} B^{\lambda}_{a} B^{\mu}_{b} B^{\nu}_{c} B^{\omega} - H_{ac} H_{bd} + H_{ad} H_{bc},$$

where H_{ab} are the components of the second fundamental tensor H and $H_{ab} = H_{ba}$.

§ 2. Some results.

Theorem 1. Let M be a hypersurface of a space of constant curvature $c \ge 0$ (resp. $c \le 0$). If the second curvature tensor is always positive (resp. negative), then $\mathfrak{X}(M)$ (resp.

Vol. 24, No. 1 Journal of Hokkaido University of Education (Section II A)

 $(-1)^m \chi(M)$) is non-negative.

Proof. Because \overline{M} is a space of constant curvature,

(5) $\bar{R}_{\lambda\mu\nu\omega} = -c(\bar{g}_{\lambda\nu}\bar{g}_{\mu\omega} - \bar{g}_{\lambda\omega}\bar{g}_{\mu\nu}).$

From (3), (4) and (5), we have

(6) $R_{abcd} = -c(g_{ac}g_{bd} - g_{ad}g_{bc}) - (H_{ac}H_{bd} - H_{ad}H_{bc}).$

We can choose the orthonormal coordinate system for a tangent space of M so that $H_{ab} = 0 (a \neq b)$ at any point of M.

With respect to this coodinate system,

(7)
$$H = \begin{bmatrix} k_1 & 0 \\ k_2 \\ 0 \\ k_n \end{bmatrix}$$

where $k_1, k_2, ..., k_n$ are the eigenvalues of H. If a, b, c, d are different mutually,

(8) $\begin{cases} -R_{abab} = c + k_a k_b, \\ R_{abac} = 0 \text{ and } R_{abcd} = 0. \end{cases}$

If, in particular, H is positive (resp. negative) and $c \ge 0$ (resp. $c \le 0$),

$$R_{abab} \geq 0$$
 (resp. $-R_{abab} \leq 0$).

In this case,

(9)
$$(-1)^m K_n = \frac{1}{2^m n!} \varepsilon^{i_1 \dots i_n} \varepsilon^{j_1 \dots j_n} R_{i_1 i_2 j_1 j_2} \dots R_{i_{n-1} i_n j_{n-1} j_n} \ge 0.$$

Comparison with (1) completes the proof. Q.E.D.

Corollary. Let M be a hypersurface of a space of constant curvature. If the sectional curvature of M is always non-negative (resp. non-negative), then $\chi(M)$ (resp. $(-1)^m \chi(M)$) is non-negative.

Similarly we have

Theorem 2. Let M be a hypersurface of a conformally flat space \overline{M} . If the sectional curvature of M is always non-negative (resp. nonpositive) and

 $\bar{R}_{\lambda\mu}B^{\lambda}_{a}B^{\mu}_{b} = \alpha g_{ab} + \beta H_{ab},$

where α and β are the functions on M, then $\chi(M)$ (resp. $(-1)^m \chi(M)$) is non-negative.

Remark 1. If $\beta \equiv 0$ in the Theorem 2, then \overline{M} is an Einstein space. In this case \overline{M} is the space of constant curvature consequently.

Remark 2. It is sufficient that a neighborhood of any point of M is immersed in \overline{M} in these theorems.

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